

A Multi-Trajectory Approach to Rare-Event Simulation

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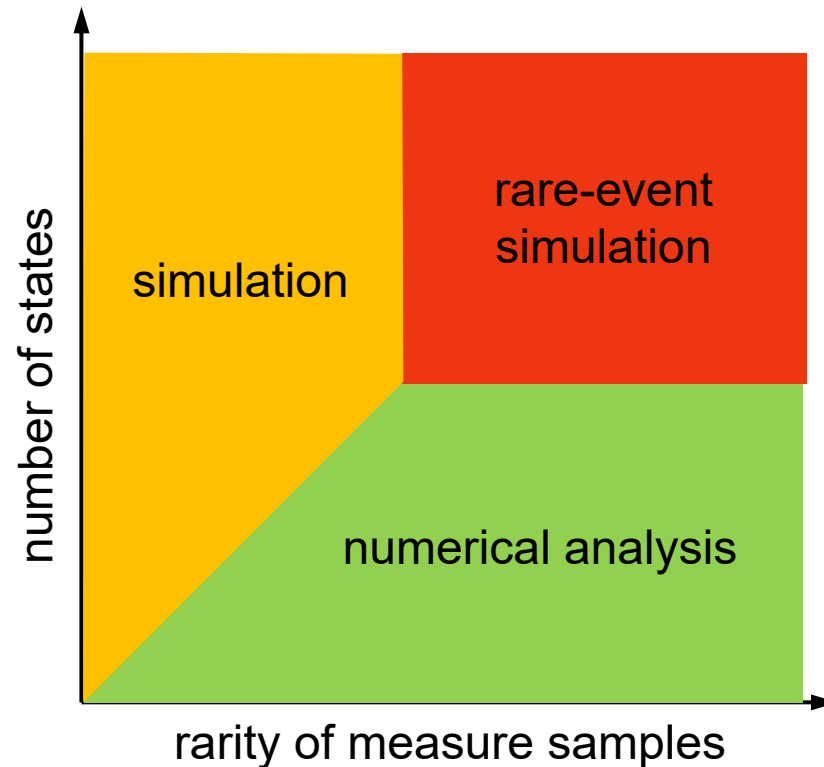
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- A hybrid multi-trajectory simulation algorithm
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Performability Evaluation

- **Applicability and Efficiency of Algorithms**
 - ▶ Two dimensions of (Markovian) problems



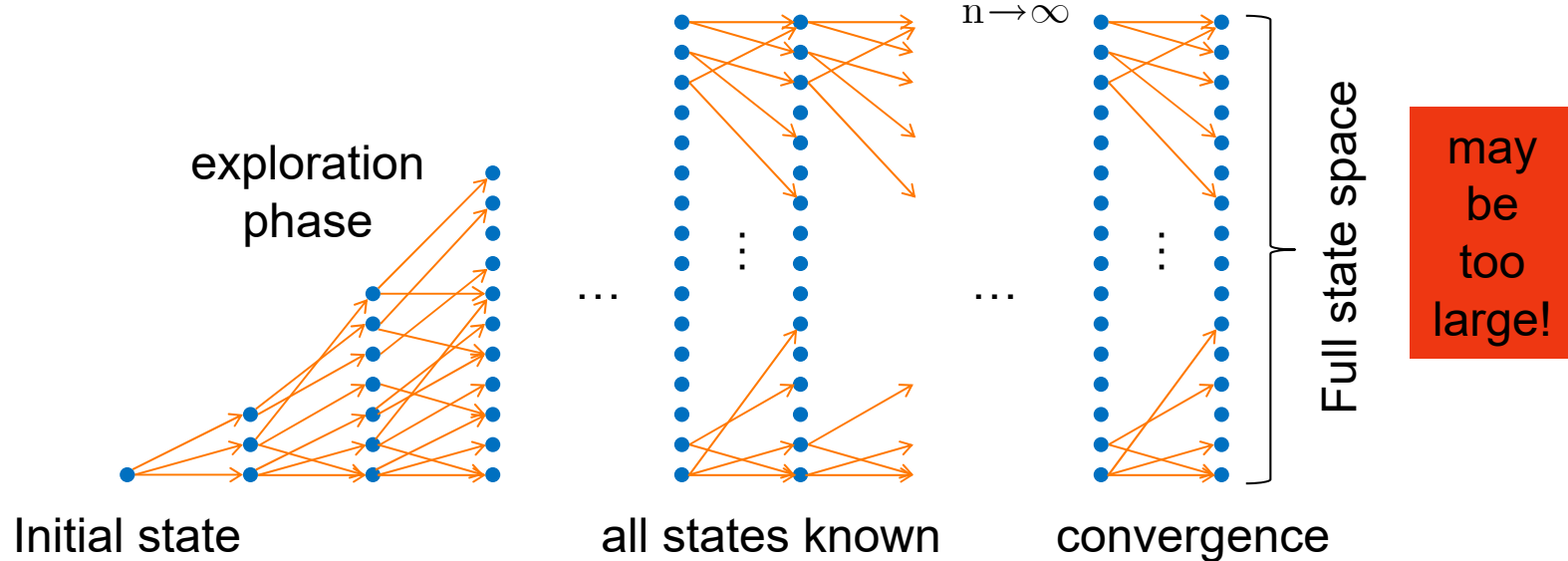
Evaluation Methods

Method 1: Numerical Analysis

- ▶ Based on full state space
- ▶ Derive and solve equations covering stochastic process X_n
- ▶ Example: DTMC $p_{ij} = P(X_n = j \mid X_{n-1} = i)$

$$p(0) \quad p(i+1) = p(i)P$$

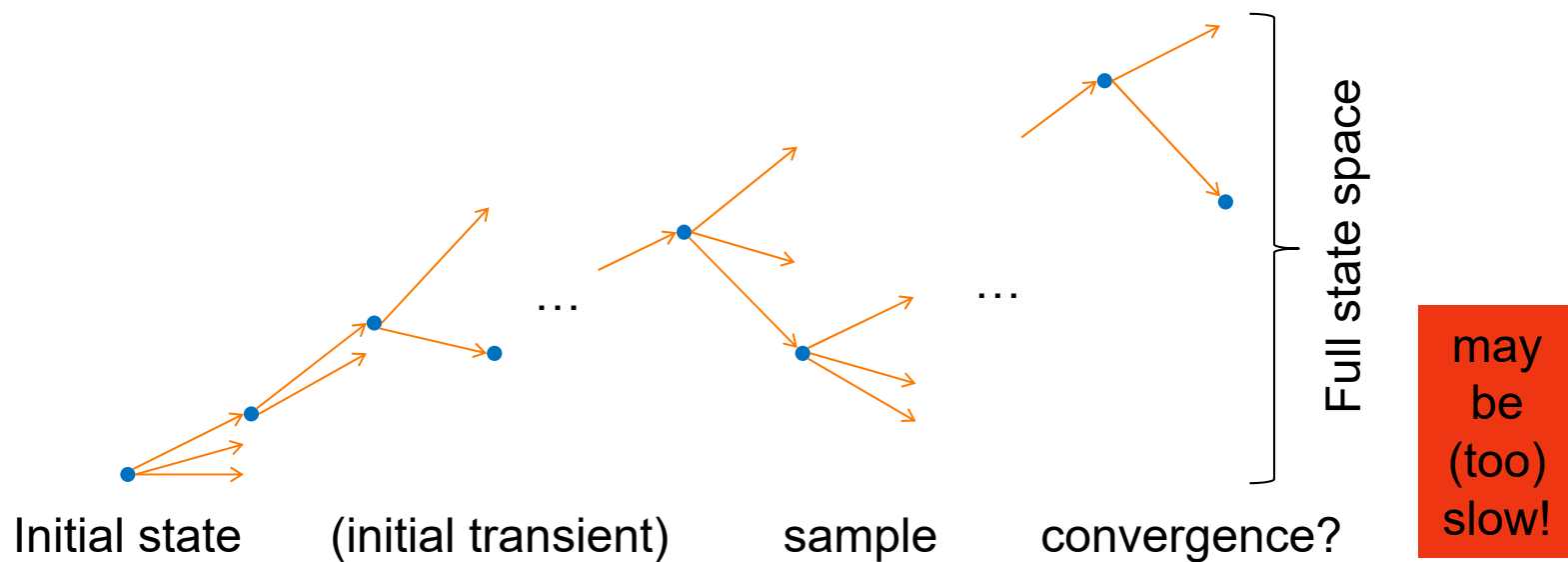
$$\lim_{n \rightarrow \infty} p(n) = \pi$$



Evaluation Methods

▪ Method 2: Simulation

- ▶ Visit states sequentially
- ▶ Choose next possible state randomly
- ▶ Collect samples on the fly
- ▶ Derive stochastic estimator (mean, variance)



Hybrid Multi-Trajectory Simulation

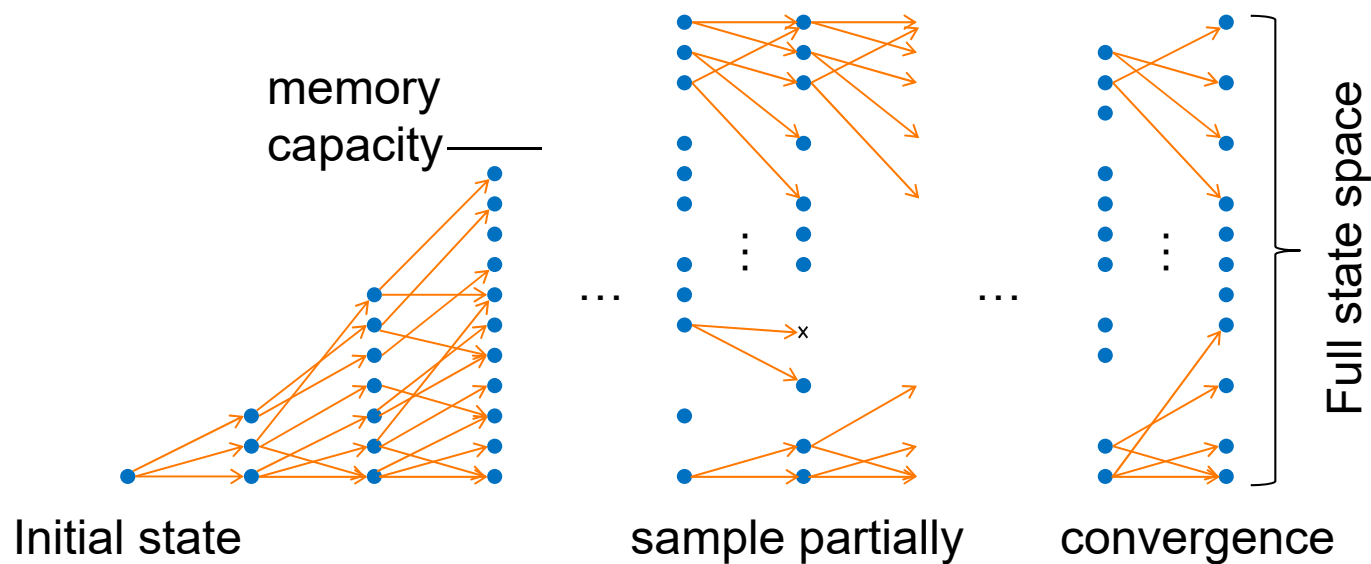
▪ **An Integrated Algorithm**

- ▶ Keep advantages of simulation *and* numerical analysis
- ▶ Work like numerical analysis, as long as memory suffices
 - **“split” particle step** following all possible state changes
 - distribute state probability over destination states
- ▶ Select state transition like simulation if not
 - **probabilistic step** of trajectory
 - merge trajectories leading to stored state (add p_i s)
 - ... other heuristics are possible (adaptive number of particles..)
- ▶ Sum of state (particle) probabilities will always be 1
 - p_i equals probability that a trajectory would have arrived at state i under the previous decisions

Hybrid Multi-Trajectory Simulation

▪ General Idea

- ▶ Keep as many states as possible
- ▶ Mix simulation and numerical analysis steps
- ▶ Treat continuous-time models via DTMC embedding



Hybrid Multi-Trajectory Simulation

- **Proofs in Previous Papers**

- ▶ Unbiasedness
- ▶ (Almost sure) convergence, at least as fast as simulation
- ▶ Based on a **unified vector-matrix framework** treating numerical analysis, simulation, and multi-trajectory in the same way

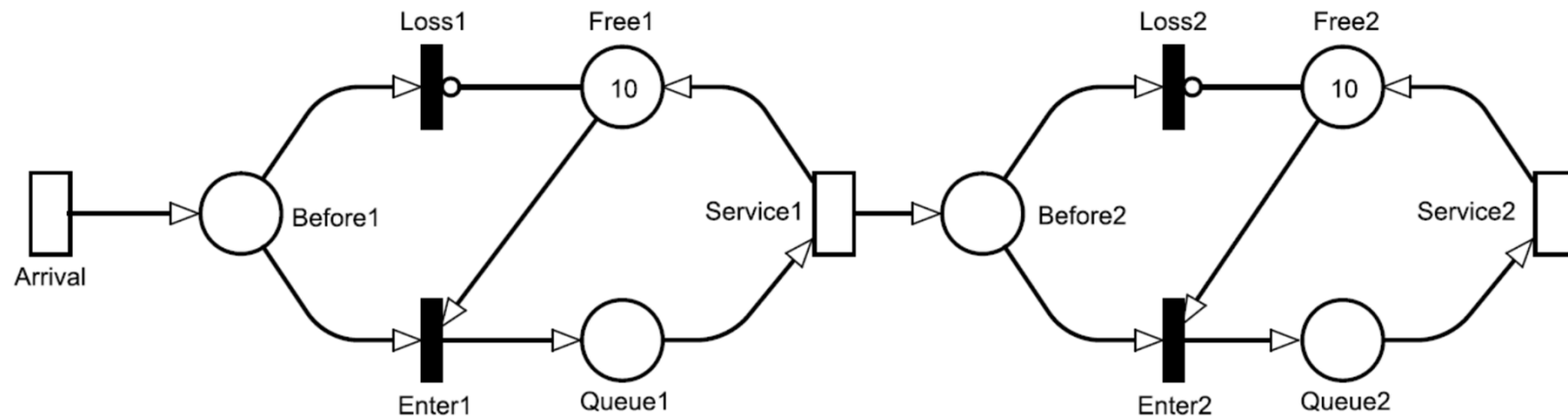
- **Contains Standard Methods as Special Cases**

- ▶ Numerical analysis: $|\text{Particles}| \geq |\text{ReachableStates}|$
- ▶ Simulation: $|\text{Particles}| = 1$

Application Example

▪ Tandem Queue Model

- ▶ Stochastic Petri net, customer losses (no blocking)
- ▶ Service rate 2 > service rate 1 > arrival rate



- ▶ Probability of #customers > n in 2nd queue: rare event

Application Example

▪ Tandem Queue Model

▶ Results

averaged over several runs, with 95% conf. interval / 5% relative error

Arrival Delay	Numeric analysis			Simulation			Adaptive Multi-Traj.		
	Result	Time	Mem.	Error	Time	Mem.	Error	Time	Mem.
1.0	1.149E-3	0.1	128	1.9%	1.2	28	0.6%	0.9	241
1.5	1.143E-4	0.1	128	1.8%	6.9	30	0.7%	0.8	240
2.0	1.378E-5	0.1	128	0.2%	35.9	76	0.8%	0.8	241
2.5	2.442E-6	0.1	128	0.3%	203.4	66	0.6%	0.8	240
3.0	5.804E-7	0.1	128	0.9%	767.5	66	0.9%	0.8	240
3.5	1.708E-7	0.1	128	1.7%	2 239.4	80	0.8%	0.8	240
4.0	5.902E-8	0.1	128	4.4%	4 476.3	56	0.9%	0.8	241
4.5	2.308E-8	0.1	128				0.5%	0.7	244
5.0	9.953E-9	0.1	128				0.5%	0.7	244

▶ Accuracy, computation time and memory consumption

Conclusion

- **Multi-Trajectory Simulation**
 - ▶ A hybrid performability evaluation algorithm integrating elements of numerical analysis and simulation
 - Mathematical framework proposed
 - Efficient compared to standard methods, useful for rare-event problems
 - Extension of splitting methods
 - ▶ Prototype tool implementation in TimeNET
 - ▶ Future work
 - Heuristics for rare-event problems with large state space
 - Extension to non-Markovian models

Further Information

- **Tool**

- ▶ <http://timenet.tu-ilmenau.de/>

- **Background and Details**

- ▶ A. Zimmermann and T. Hotz: *Integrating simulation and numerical analysis in the evaluation of generalized stochastic Petri nets*, ACM TOMACS 29(4) 2019.

- **Application**

- ▶ A. Zimmermann, T. Hotz, V. Hädicke, and M. Friebe: *Analysis of safety-critical cloud architectures with multi-trajectory simulation*, accepted for publication at RAMS 2022.

```

repeat (* main simulation loop *)
  while  $|Particles| > 0$  do
    Select any  $p \in Particles$  ;  $Particles := Particles \setminus \{p\}$ 
     $w := p.weight$  ;  $m := p.marking$ 
     $\mathcal{T}_{ena} :=$  set of all transitions enabled in marking  $m$ 

```

▪ Algorithm

```

(* rate reward and sojourn time *)
 $WeightSum := \sum_{tr \in \mathcal{T}_{ena}} \lambda(tr)$ 
 $Reward += \frac{w}{WeightSum} RateReward^{rvar}(m)$ 
 $SimTime += \frac{w}{WeightSum}$ 

```

```

(* decision heuristic, here: only split if enough space *)
if  $|Particles| + |Particles'| + |\mathcal{T}_{ena}| > N$  then (* don't split *)
  Select any  $tr \in \mathcal{T}_{ena}$  randomly
   $\mathcal{T}_{ena} := \{tr\}$  ;  $WeightSum := \lambda(tr)$ 

```

```

(* fire transition(s) *)
for  $\forall tr \in \mathcal{T}_{ena}$  do
   $m' := FireTransition(m, tr)$ 
  if  $m' \notin Particles'$  then (* add new particle *)
     $Particles' := Particles' \cup \{(m', 0)\}$ 
  (* merge particle weight *)
   $Particles'(m').weight += \frac{w}{WeightSum} \lambda(tr)$ 
  (* impulse reward for fired transition *)
   $Reward += \frac{w}{WeightSum} ImpulseReward^{rvar}(m, tr)$ 

```

```

(* full particle set finished *)
 $Particles := Particles'$  ;  $Particles' := \{\}$ 
Collect measure sample with value  $\frac{Reward}{SimTime}$ 

```