Limit Theorems for Cloning Algorithms

Stefan Grosskinsky

TU Delft - DIAM

May 21, 2021

RESIM 2021

 299

The Team

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- L. Angeli, S. Grosskinsky, A.M. Johansen. Limit theorems for cloning algorithms. Stoch. Proc. Appl. 138: 117-152 (2021)
- L. Angeli, S. Grosskinsky, A.M. Johansen, A. Pizzoferrato. Rare event simulation for stochastic dynamics in continuous time. Journal of Statistical Physics 176(5): 1185–1210 (2019)

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Outline

- Motivation from statistical physics
- SMC for continuous-time jump processes (Feynman-Kac models)
- Cloning algorithm, comparison to other particle approximations
- **Current fluctuations for IPS**

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Motivation from Statistical Physics

Current large deviations in lattice gases/dynamic phase transitions

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 $J(\rho)$ typical current , $j > J(\rho)$ atypical current correlated trajectories

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Motivation from Statistical Physics

Current large deviations in lattice gases/dynamic phase transitions

 $J(\rho)$ typical current , $j < J(\rho)$ atypical current **phase separation**

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Sequential Monte Carlo methods

[D. Alvares, PhD thesis, researchgate.net]

Particle filters

[Crisan, Lyons (1997); Del Moral, Miclo (2000); Del Moral, Doucet, Jasra (2006); Rousset (2006); . . .]

dynamic rare events/cloning algorithms

[Giardina, Kurchan, Peliti (2006); Lecomte, Tailleur (2007); Pérez-Espirages, Hurtado (2019); . . .]

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 298

Mathematical setting

Continuous-time Markov jump process $(X_t : t \geq 0)$, \mathbb{P}_r , \mathbb{E}_r ${\bf state \ space \ \ \ \ } E,$ locally compact Polish space (e.g. $\mathbb{R}^d,\,\mathbb{N}_0^L$ or $\{0,1\}^{\mathbb{Z}})$ transition kernel $W(x, dy)$, $w(x) = \int_E W(x, dy) \le \bar{w} < \infty$

generator $\mathcal{L}f(x) =$ $\int_{E} W(x, dy)[f(y) - f(x)], \quad f \in C_b(E), x \in E$

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generator $\mathcal{L}f(x) =$ $\int_{E} W(x, dy)[f(y) - f(x)], \quad f \in C_b(E), x \in E$ distribution

$$
\mu_t(f) := \mathbb{E}_{\mu_0}\big[f(X_t)\big] \quad \text{with} \quad \frac{d}{dt}\mu_t(f) = \mu_t(\mathcal{L}f) \ , \quad f \in C_b(E)
$$

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$$

Assumption. Asymptotic stability

There exist $C > 0$, $\alpha \in (0,1)$, such that for all $\mu_0 \in \mathcal{P}(E)$

 $\|\mu_t(f) - \mu_\infty(f)\| \le C \|f\| \alpha^t , \quad t \ge 0 ,$

where $\mu_{\infty} \in \mathcal{P}(E)$ is the unique **stationary distribution**.

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Feynman-Kac model potential $\mathcal{V} \in C_b(E)$, $\mathcal{L}^{\mathcal{V}} f(x) := \mathcal{L} f(x) + \mathcal{V}(x) f(x)$

Feynman-Kac measures $(\nu_t : t \ge 0)$ where $\nu_0 = \mu_0$

$$
\nu_t(f) := \mathbb{E}_{\mu_0} \Big[f(X_t) \, e^{\int_0^t \mathcal{V}(X_s) ds} \Big] \quad \text{with} \quad \frac{d}{dt} \nu_t(f) = \nu_t(\mathcal{L}^{\mathcal{V}} f)
$$

non-conservative $\mathcal{L}^{\mathcal{V}} 1(x) = 0 + \mathcal{V}(x) \neq 0$

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principal eigenvalue $\lambda \in \mathbb{R}$ with left eigenvector $\mu_{\infty}^{\mathcal{V}} \in \mathcal{P}(E)$

$$
\lim_{t \to \infty} \frac{1}{t} \log \nu_t(1) = \lambda = \mu_{\infty}^{\mathcal{V}}(\mathcal{L}^{\mathcal{V}} 1) = \mu_{\infty}^{\mathcal{V}}(\mathcal{V})
$$

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$$

normalized measures
$$
\mu_t^{\mathcal{V}}(f) = \mu_t(f) := \nu_t(f)/\nu_t(1)
$$

$$
\frac{d}{dt}\mu_t(f) = \mu_t\left(\mathcal{L}f + \mathcal{V}f - \mu_t(\mathcal{V})f\right) \tag{*}
$$

$$
\underset{\text{S. Grosskinsky (TU Deft)}}{\text{asymptotic stability}} \quad \underset{\text{Limit Theorems for Cloning}}{\big\|\mu_t(f) - \mu^{\mathcal{V}}_{\infty}(f)\big\|} \leq C \|f\|\alpha^t \text{ for } t_{\text{A}} = t \geq 0, \quad t \geq \frac{\alpha}{\beta^0}, \quad t \geq \frac{\alpha}{\beta^0} \in \{0,1\}_{\text{A}} \quad \text{for } t \geq 0, \quad t \geq 0.
$$

McKean interpretation

$$
\frac{d}{dt}\mu_t(f) = \mu_t(\mathcal{L}f + \mathcal{V}f - \mu_t(\mathcal{V})f) = \mu_t(\mathcal{L}f + \widetilde{\mathcal{L}}_{\mu_t}f)
$$

McKean process $(\widetilde{X}(t): t \geq 0)$ on E with generator $\mathcal{L}_u := \mathcal{L} + \widetilde{\mathcal{L}}_u$ $\widetilde{\mathcal{L}}_{\mu}f(x) = \int_{E} \widetilde{W}(x, y)\mu(dy) (f(y) - f(x)), \quad \mu \in \mathcal{P}(E)$ such that $\mu(\mathcal{L}_{\mu}f) = \mu(\mathcal{V}f) - \mu(\mathcal{V})\mu(f)$.

holds if and only if $\mu\big(W(.,x)-W(x,.)\big)=\mathcal{V}(x)-\mu(\mathcal{V})$

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Sufficient condition $\widetilde{W}(y, x) - \widetilde{W}(x, y) = \mathcal{V}(x) - \mathcal{V}(y)$

Examples for constant $c \in \mathbb{R}$ or $c = \mu(\mathcal{V})$ (using $g = g^+ - g^-$)

1.
$$
\widetilde{W}_1(x,y) = (\mathcal{V}(x) - c)^{-} + (\mathcal{V}(y) - c)^{+}
$$

2.
$$
\widetilde{W}_2(x,y) = (\mathcal{V}(y) - \mathcal{V}(x))^+
$$

3.
$$
\widetilde{W}_3(x,y) = \frac{(\mathcal{V}(x) - \mu(\mathcal{V}))^-(\mathcal{V}(y) - \mu(\mathcal{V}))^+}{\mu(\mathcal{V} - \mu(\mathcal{V}))^+}
$$

Particle approximations

 $(\underline{\xi}_t:t\geq 0)$ on E^M with \mathbb{P}^M , \mathbb{E}^M , M 'clones' $\xi_t^1,\ldots \xi_t^M$ run in parallel

Estimate μ_t by the **empirical measure** $\mu_t^M := m(\underline{\xi}_t)$ with

$$
m(\underline{x})(dy):=\frac{1}{M}\sum_{i=1}^M \delta_{x_i}(dy)\quad \text{as a distribution on}\ E\ .
$$

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Mean-field approximations for a given McKean model $\mathcal{L}_{\mu} = \mathcal{L} + \widetilde{\mathcal{L}}_{\mu}$

$$
\mathcal{L}^M F(\underline{x}) = \sum_{i=1}^M \mathcal{L}_{m(\underline{x})}^{(i)} F(\underline{x}), \quad F \in C_b(E^M)
$$

where $\mathcal{L}_{m}^{(i)}$ $\frac{d^{(i)}}{m(\underline{x})}$ acts on $x^i \mapsto F(x^1,..,x^i,..,x^M).$

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$$

where $\mathcal{L}_{m}^{(i)}$ $\frac{d^{(i)}}{m(\underline{x})}$ acts on $x^i \mapsto F(x^1,..,x^i,..,x^M).$

$$
F(\underline{x}) = f(x_i) \Rightarrow \mathcal{L}^M f(x_i) = \mathcal{L}_{m(\underline{x})} f(x_i)
$$

$$
F(\underline{x}) = \frac{1}{M} \sum_{i=1}^M f(x_i) = m(\underline{x})(f) \Rightarrow \mathcal{L}^M m(\underline{x})(f) = m(\underline{x})(\mathcal{L}_{m(\underline{x})}f)
$$

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Cloning/Killing interpretation

$$
\mathcal{L}^{M} F(\underline{x}) = \sum_{i=1}^{M} \int_{E} W(x_{i}, dy) (F(\underline{x}^{i,y}) - F(\underline{x}))
$$

+
$$
\sum_{i=1}^{M} (\mathcal{V}(x_{i}) - c)^{+} \frac{1}{M} \sum_{j=1}^{M} (F(\underline{x}^{j,x_{i}}) - F(\underline{x}))
$$

+
$$
\sum_{i=1}^{M} (\mathcal{V}(x_{i}) - c)^{-} \frac{1}{M} \sum_{j=1}^{M} (F(\underline{x}^{i,x_{j}}) - F(\underline{x}))
$$

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 299

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Martingale characterization

Stochastic analysis to characterize fluctuations:

$$
\mathcal{M}_F^M(t) := F\left(\underline{\xi}_t\right) - F\left(\underline{\xi}_0\right) - \int_0^t \mathcal{L}^M F\left(\underline{\xi}_s\right) ds
$$

is a martingale on $\mathbb R$ with (predictable) quadratic variation

$$
\langle \mathcal{M}_F^M \rangle(t) = \int_0^t \Gamma^M F\big(\underline{\xi}_s\big) ds \ ,
$$

and carré du champ $\Gamma^M F(\underline{x}):= \mathcal{L}^M F^2(\underline{x}) - 2F(\underline{x})\mathcal{L}^M F(\underline{x})$.

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$$

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Mean-field approximations with McKean model \mathcal{L}_{μ} and Γ_{μ}

$$
F(\underline{x}) = f(x_i) \Rightarrow \Gamma^M F(\underline{x}) = \Gamma_{m(\underline{x})} f(x_i)
$$

$$
F(\underline{x}) = m(\underline{x})(f) \Rightarrow \Gamma^M F(\underline{x}) = \frac{1}{M} m(\underline{x})(\Gamma_{m(\underline{x})} f).
$$

 209

Main convergence result

Assumptions

For a given McKean model \mathcal{L}_μ on E we assume that the sequence of particle approximations $(\xi_{\scriptscriptstyle{+}}:t\geq 0)$ on E^M with generators \mathcal{L}^M (and associated $\Gamma^M)$ satisfy for all $f \in C_b(E)$ and $F(\underline{x}) = m(\underline{x})(f)$

(A1)
$$
\mathcal{L}^M F(\underline{x}) = m(\underline{x})(\mathcal{L}_{m(.)}f)
$$
 for all $M \ge K$
\n(A2) $\Gamma^M F(\underline{x}) = \frac{1}{M} m(\underline{x})(G_{m(.)}f) + O(\frac{1}{M^2})$ as $M \to \infty$
\nwhere $\sup_{x \in \mathbb{R}^m} \sup_{x \in \mathbb{R}^m} ||G||(f, f)|| \le \infty$ (Consistency)

(A2)
$$
\Gamma^{M} F(\underline{x}) = \frac{1}{M} m(\underline{x}) (G_{m(1)}f) + O(\frac{1}{M^2}) \text{ as } M \to \infty
$$

where $\sup_{\mu \in \mathcal{P}(E)} \sup_{\|f\| \le 1} \|G_{\mu}(f, f)\| < \infty$ (Concentration)

(A3) almost surely, $\sup_{t>0} |\{1 \le i \le M : \xi_t^i \ne \xi_{t-}^i\}| \le K$ $_{t\geq 0}$

(bounded jumps)

(A4) $\xi_0^1, \ldots, \xi_0^M \sim \mu_0$ i.i.d.r.v.s

(initial condition)

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Main convergence result

Convergence of estimators (LLN)

Assume asymptotic stability and (A1) to (A4) for a particle approximation μ^M_t . Then for all $f \in C_b(E)$ the systematic error is bounded as

$$
\sup_{t\geq 0}\Big|\mathbb{E}^M\Big[\mu_t^M(f)\Big]-\mu_t(f)\Big|\leq \frac{C\|f\|}{M}\quad\text{for all M large enough }\,,
$$

where $\mu_t(f)$ solves (\star) , and the random error for all $p \geq 2$ as

$$
\sup_{t\geq 0} \mathbb{E}^M \left[\left| \mu_t^M(f) - \mathbb{E}^M\big[\mu_t^M(f)\big] \right|^p \right]^{1/p} \leq \frac{C_p \|f\|}{\sqrt{M}}
$$

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$$

Unbiased estimators for unnormalized measures

$$
\nu_t^M(f):=\nu_t^M(1)\mu_t^M(f)\quad\text{with}\quad \nu_t^M(1):=\exp\left(\,\int_0^t\mu_s^M(\mathcal{V})ds\right)\,,
$$

where $\mathbb{E}^{M}\big[\nu_{t}^{M}(f)\big]=\nu_{t}(f)$ for all $t\geq0, M\geq1, f\in C_{B}(E).$ $t\geq0, M\geq1, f\in C_{B}(E).$ $t\geq0, M\geq1, f\in C_{B}(E).$ @ ▶ ◀ 로 ▶ ◀ 로

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Sketch of the proof

$$
\begin{aligned}\n\text{opopagator} \quad \Theta_{t,T} f(x) &:= \frac{P_{T-t}^{\mathcal{V}} f(x)}{\mu_t (P_{T-t}^{\mathcal{V}})^{\mathcal{V}}} \quad \text{s. th.} \quad \mu_T(f) = \mu_t \big(\Theta_{t,T} f\big) \\
\text{or} \quad \mathbb{E}^M \Big[\big|\mu_T^M(f) - \mu_T(f)\big|^p \Big]^{1/p} \leq E^M \Big[\big|\mu_T^M(f) - \mu_t^M \big(\Theta_{t,T} f\big)\big|^p \Big]^{1/p} \\
&\quad + E^M \Big[\big|\mu_t^M \big(\Theta_{t,T} f\big) - \mu_T(f)\big|^p \Big]^{1/p}\n\end{aligned}
$$

- choose $T t \propto \log M$ and use asymptotic stability
- martingale decomposition for $F(x) = m(x)(f)$

$$
\mu_T^M(f) - \mu_t^M(f) = \mathcal{M}_f^M(T - t) + \int_t^T \mathcal{L}_{m(\underline{\xi}_s)}(f) ds
$$

• connect **predictable QV** with QV (bounded jumps $\overline{A3}$)

 \bullet use BDG inequality to bound moments of martingales (A2)

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Asymptotic variance

Partial result

Assume asymptotic stability and (A1) to (A4) for a particle approximation μ_t^M , such that for some $T > 0$ and all $0 \leq s \leq T$, $f \in C_b(E)$

 $\mu_s^M\bigl(G_{\mu_s^M}(f)\bigr)\to \mu_s\bigl(G_{\mu_s}(f)\bigr) \qquad \text{in a strong enough sense(?)}.$

Then $V^M_T(f):=\sqrt{M}\big(\mu^M_T(f)-\mu_T(f)\big)\to V_T(f)$ in law as $M\to\infty.$ Here $V_T(f)$ is a centred Gaussian with asymptotic variance

$$
\mathbb{E}\big[V_T(f)^2\big] = \mu_0((\Theta_{0,T}\bar{f})^2) + \int_0^T \mu_s\big(G_{\mu_s}(\Theta_{s,T}\bar{f})\big)ds,
$$

where Θ_t Tf is the propagator for μ_t and $\bar{f} = f - \mu_t(f)$.

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More general particle approximations

Mean-field approximation

Cloning algorithm [Giardina, Kurchan, Peliti (2006); Lecomte, Tailleur (2007)]

The cloning algorithm

cloning distribution π_x on subsets of $\{1, \ldots, M\}$ ${\cal L}_c^M F(\underline{x}):=\!\sum\limits_{}^M$ $\frac{i=1}{i}$ Z $\int_E W(x_i, dy) \sum_{A \subset \Omega}$ $A \subseteq \{1,..,M\}$ $\pi_{x_i}(A)\big(F(\underline{x}^{A,x_i;i,y})-F(\underline{x})\big)$ $+\sum_{1}^{M}$ $\frac{i=1}{i}$ $(\mathcal{V}(x_i) - c) = \frac{1}{M}$ \sum $j=1$ $(F(\underline{x}^{i,x_j})-F(\underline{x}))$

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The cloning algorithm

cloning distribution
$$
\pi_x
$$
 on subsets of $\{1, ..., M\}$
\n
$$
\mathcal{L}_c^M F(\underline{x}) := \sum_{i=1}^M \int_E W(x_i, dy) \sum_{A \subseteq \{1, ..., M\}} \pi_{x_i}(A) \big(F(\underline{x}^{A, x_i; i, y}) - F(\underline{x}) \big)
$$
\n
$$
+ \sum_{i=1}^M \big(V(x_i) - c \big) \frac{1}{M} \sum_{j=1}^M \big(F(\underline{x}^{i, x_j}) - F(\underline{x}) \big)
$$

choose $\pi_x(A) = \pi_x(|A|) / {M \choose |A|} = 0$ if $|A| > K$ and (A3)

$$
R(x) := \sum_{n=0}^{M} n \pi_x(n) = \frac{(\mathcal{V}(x) - c)^+}{w(x)}, \quad Q(x) := \sum_{n=0}^{M} n^2 \pi_x(n) \le C < \infty.
$$

For
$$
F(\underline{x}) = m(\underline{x})(f)
$$
 we get
\n• $\mathcal{L}_c^M F(\underline{x}) = \mathcal{L}^M F(\underline{x}) = m(\underline{x})(\mathcal{L}_{m(.)}f)$ (A1)

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The cloning algorithm $\Gamma_c^M F(\underline{x}) = \frac{1}{M} m(\underline{x}) \Big(\overline{\Gamma_{m(.)} f + w(Q - R)} \Big(\overline{\ell_{m(.)} f(.) \Big)^2 + O(1)} \Big) + O\big(\frac{1}{M^2}\big)$ $=G_{m(.)(f)}$ where $\ell_{\mu} f(x) := \int_{E} (f(y) - f(x)) \mu(dy)$ (A2)

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The cloning algorithm $\Gamma_c^M F(\underline{x}) = \frac{1}{M} m(\underline{x}) \Big(\overline{\Gamma_{m(.)} f + w(Q - R)} \Big(\overline{\ell_{m(.)} f(.) \Big)^2 + O(1)} \Big) + O\big(\frac{1}{M^2}\big)$ $=G_{m(.)(f)}$ where $\ell_{\mu} f(x) := \int_{E} (f(y) - f(x)) \mu(dy)$ (A2) generic choice $\sqrt{ }$ Į X $R(x) - [R(x)]$, $n = [R(x)] + 1$ $[R(x)] + 1 - R(x), n = [R(x)]$ 0 , otherwise

Selection intensities for McKean models, to minimize $\Gamma_{m(.)}f$

1.
$$
\widetilde{W}_1(x, y) = (\mathcal{V}(x) - c)^{-} + (\mathcal{V}(y) - c)^{+}
$$

\n2. $\widetilde{W}_2(x, y) = (\mathcal{V}(y) - \mathcal{V}(x))^{+}$
\n3. $\widetilde{W}_3(x, y) = \frac{(\mathcal{V}(x) - \mu(\mathcal{V}))^{-} (\mathcal{V}(y) - \mu(\mathcal{V}))^{+}}{\mu(\mathcal{V} - \mu(\mathcal{V}))^{+}}$

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The cloning algorithm $\Gamma_c^M F(\underline{x}) = \frac{1}{M} m(\underline{x}) \Big(\overline{\Gamma_{m(.)} f + w(Q - R)} \Big(\overline{\ell_{m(.)} f(.) \Big)^2 + O(1)} \Big) + O\big(\frac{1}{M^2}\big)$ $=G_{m(.)(f)}$ where $\ell_{\mu} f(x) := \int_{E} (f(y) - f(x)) \mu(dy)$ (A2) $\sqrt{ }$ $R(x) - [R(x)]$, $n = [R(x)] + 1$

generic choice

$$
\pi_x(n) = \begin{cases}\nR(x) - \lfloor R(x) \rfloor, & n = \lfloor R(x) \rfloor + \\
\lfloor R(x) \rfloor + 1 - R(x), & n = \lfloor R(x) \rfloor \\
0, & \text{otherwise}\n\end{cases}
$$

Selection intensities for McKean models, to minimize $\Gamma_{m(.)} f$

1.
$$
S_1(\underline{x}) = \sum_{i=1}^{M} |\mathcal{V}(x_i) - c| \Rightarrow c = \text{median}(\mathcal{V}(\underline{x}))
$$

2.
$$
S_2(\underline{x}) = \frac{1}{2} \sum_{i,j=1}^{M} |\mathcal{V}(x_i) - \mathcal{V}(x_j)| \le S_1(\underline{x})
$$

3.
$$
S_3(\underline{x}) \le S_2(\underline{x})
$$

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 $\left\{ \begin{array}{ccc} 1 & 0 & 0 \\ 0 & 1 & 0 \end{array} \right.$

Dynamic large deviations

Continuous-time Markov jump process $(X_t : t \geq 0)$ with path space (Ω, \mathbb{P})

Additive path space observable , $g\in C_b(E^2)$, $h\in C_b(E)$

$$
A_T[\omega] := \sum_{\substack{t \le T \\ \omega(t-) \neq \omega(t)}} g(\omega(t-), \omega(t)) + \int_0^T h(\omega(t)) dt
$$

Assume that A_T fulfills a large deviation principle such that

$$
\mathbb{P}\big[A_T/T \approx a\big] \asymp e^{-T\,I(a)} \quad \text{ as } T \to \infty \,\, ,
$$

with rate function $I(a) \in [0, \infty]$.

Assume $I(a)$ is **convex**, then $I(a) = \sup_{k \in \mathbb{R}}$ $(ka - \lambda_k)$ for all $a \in \mathbb{R}$,

given by the Legendre transform of the **SCGF**

$$
\lambda_k := \lim_{T \to \infty} \frac{1}{T} \log \mathbb{E}_{\mu_0} \big[e^{kA_T} \big] \in \mathbb{R} \;, \quad k \in \mathbb{R} \;.
$$

 $[Chapterite, Touchette (2015)]$ $[Chapterite, Touchette (2015)]$

SCGF and tilted generator

$$
\nu_T^k(f) = \mathbb{E}_{\mu_0} \left[f(X_T) \exp \left(k \sum_{t \le T} g(X_{t-}, X_t) + k \int_0^T h(X_t) dt \right) \right]
$$

 λ_k is principal eigenvalue of the **tilted generator**

$$
\mathcal{L}_k f(x) := \int_E W(x, dy) \left[e^{kg(x, y)} f(y) - f(x) \right] + kh(x) f(x)
$$

$$
= \underbrace{\int_E W_k(x, dy) \left[f(y) - f(x) \right]}_{\widehat{\mathcal{L}}_k f(x)} + \mathcal{V}_k(x) f(x)
$$

with modified rates $W_k(x, dy) = W(x, dy)e^{kg(x, y)}$ for the jump part \mathcal{L}_k , and diagonal potential $\qquad {\cal V}_k(x) = \int_E$ $W(x, dy) [e^{kg(x,y)} - 1] + kh(x)$.

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$$

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and diagonal potential
$$
\mathcal{V}_k(x) = \int_E W(x, dy) \big[e^{kg(x,y)} - 1 \big] + kh(x) .
$$

For all $\nu_0^k = \mu_0$, **asymptotic stability** implies that as $t \to \infty$

$$
\lambda_k(t) := \frac{1}{t} \ln \nu_t^k(1) = \frac{1}{t} \int_0^t \mu_s^k(\mathcal{V}_k) ds \rightarrow \lambda_k = \mu_\infty^k(\mathcal{V}_k)
$$

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SCGF and tilted generator

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\nu_T^k(f) = \mathbb{E}_{\mu_0} \left[f(X_T) \exp \left(k \sum_{t \le T} g(X_{t-}, X_t) + k \int_0^T h(X_t) dt \right) \right]
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$$
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$$

with modified rates $W_k(x, dy) = W(x, dy)e^{kg(x, y)}$ for the jump part \mathcal{L}_k , and diagonal potential $\qquad {\cal V}_k(x) = \int_E$ $W(x, dy) [e^{kg(x,y)} - 1] + kh(x)$.

Furthermore, with $\lambda_k(u,t) := \frac{1}{t-u} \int_u^t \mu_s^k(\mathcal{V}_k) ds$

$$
\left|\lambda_k(bt,t)-\lambda_k\right|\leq C\|\mathcal{V}_k\|\frac{\alpha^{bt}}{t}\quad\text{for all }b\in[0,1)\;.
$$

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Particle estimators for SCGF

 $\mathsf{particle}\; \mathsf{approximation}\;(\underline{\xi}_t:t\ge 0)$, with empirical measure μ^M_t

$$
\text{Estimator} \quad \Lambda^M_k(u,t) := \frac{1}{t-u} \int_u^t ds \frac{1}{M} \sum_{i=1}^M \mathcal{V}_k(\xi^i_s)
$$

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$$

Error bounds for cloning algorithm

Assume asymptotic stability and (A1) to (A4). Then there exist $C, C_p > 0$ such that for all $b \in [0, 1)$ the systematic error is

$$
\Big| \mathbb{E}^M\big[\Lambda^M_k(bt,t) \big] - \lambda_k \Big| \leq C \| \mathcal{V}_k \| \Big(\frac{1}{M} + \frac{\alpha^{bt}}{t} \Big) \quad \text{for all M,t large enough },
$$

and the random error for all $p > 2$ is

$$
\sup_{t\geq 0}\mathbb{E}^M\Big[\Big|\Lambda_k^M(t)-\mathbb{E}^M\big[\Lambda_k^M(t)\big]\Big|^p\Big]^{1/p}\leq \frac{C_p\|\mathcal{V}_k\|}{\sqrt{M}}\quad\text{for all M large enough}\;.
$$

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The cloning factor

Jump process $\left(C_t^M:t\geq 0\right)$ on \mathbb{R}^+ with $C_0^M=1$, where at each selection event of size $n > -1$ at time t the value is updated as

 $C_t^M = C_{t-}^M(1 + n/M)$.

joint process $(\underline{\xi}_t, C_t^M)$ is Markov with ${\bf extended}$ generator $\quad \overline{\mathcal{L}}_c^M F(\underline{x}, c)$

 $\mathbb{E}^M[C_t^M]\,e^{tc}=\nu_t(1)$, unbiased estimator for $e^{\lambda_k t}$ for large t

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- joint process $(\underline{\xi}_t, C_t^M)$ is Markov with ${\bf extended}$ generator $\quad \overline{\mathcal{L}}_c^M F(\underline{x}, c)$
- $\mathbb{E}^M[C_t^M]\,e^{tc}=\nu_t(1)$, unbiased estimator for $e^{\lambda_k t}$ for large t
- Observing only the cloning factor with $F(\underline{x}, c) = \log c$ we get

$$
\overline{\mathcal{L}}_c^M F(\underline{x}, c) = m(\underline{x})(\mathcal{V}_k - c) + O\left(\frac{1}{M}\right)
$$

due to bounded clone event size $n(A4)$

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The cloning factor

Jump process $\left(C_t^M:t\geq 0\right)$ on \mathbb{R}^+ with $C_0^M=1$, where at each selection event of size $n > -1$ at time t the value is updated as

 $C_t^M = C_{t-}^M(1 + n/M)$.

- joint process $(\underline{\xi}_t, C_t^M)$ is Markov with ${\bf extended}$ generator $\quad \overline{\mathcal{L}}_c^M F(\underline{x}, c)$
- $\mathbb{E}^M[C_t^M]\,e^{tc}=\nu_t(1)$, unbiased estimator for $e^{\lambda_k t}$ for large t
- Observing only the cloning factor with $F(\underline{x}, c) = \log c$ we get

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\overline{\mathcal{L}}_c^M F(\underline{x}, c) = m(\underline{x})(\mathcal{V}_k - c) + O\left(\frac{1}{M}\right)
$$

due to bounded clone event size $n(A4)$

• Martingale characterization provides new estimator

$$
\bar{\Lambda}^M_k(u,t) := \frac{1}{t-u} \log \frac{C_t^M}{C_u^M} + c = \Lambda^M_k(u,t) + \frac{\mathcal{M}^M_C(t) - \mathcal{M}^M_C(u)}{t-u} + O\left(\frac{1}{M}\right)
$$

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Current large deviations for IPS

 \bullet IPS with generator $z \in \mathbb{T}_L$ $p u(\eta_z, \eta_{z+1}) (f(\eta^{z,z+1}) - f(\eta))$ $+q u(\eta_z, \eta_{z-1}) (f(\eta^{z,z-1}) - f(\eta))$

cont.-time jump process on state space $E=\mathbb{N}_0^L$, NN dynamics with PBC

• finite state CTMC with fixed number of particles

 \Rightarrow LDP for $(A_T)_T$ due to contraction [Bertini, Faggionato, Gabrielli (2015)]

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Current large deviations for IPS

IPS with generator $z \in \mathbb{T}_L$ $p u(\eta_z, \eta_{z+1}) (f(\eta^{z,z+1}) - f(\eta))$ $+q u(\eta_z, \eta_{z-1}) (f(\eta^{z,z-1}) - f(\eta))$

cont.-time jump process on state space $E=\mathbb{N}_0^L$, NN dynamics with PBC

• finite state CTMC with fixed number of particles \Rightarrow LDP for $(A_T)_T$ due to contraction [Bertini, Faggionato, Gabrielli (2015)] assume $\sum_z u(\eta_z, \eta_{z+1}) = \sum_z u(\eta_z, \eta_{z-1})$ and $p+q=1$ total exit rate $w(\eta) = \sum_{z \in \mathbb{T}_L} u(\eta_z, \eta_{z+1})$ $w_k(\eta) = Q_k w(\eta)$ where $Q_k = pe^k + qe^{-k}$ potential $V_k(\eta) = (Q_k - 1)w(\eta)$

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Current large deviations for IPS

IPS with generator $z \in \mathbb{T}_L$ $p u(\eta_z, \eta_{z+1}) (f(\eta^{z,z+1}) - f(\eta))$ $+q u(\eta_z, \eta_{z-1}) (f(\eta^{z,z-1}) - f(\eta))$

cont.-time jump process on state space $E=\mathbb{N}_0^L$, NN dynamics with PBC

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potential $V_k(\eta) = (Q_k - 1)w(\eta)$

Example inclusion process with $u(n,m) = n(d+m)$

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Comparison of algorithms

SCGF for current fluctuations in a stochastic lattice gas cloning algorithm $\widetilde{W}(x, y) = (\mathcal{V}_k(y) - c)^+ + (\mathcal{V}_k(x) - c)^-, c = 0$ mean-field approximation $\widetilde{W}(x,y) = (\mathcal{V}(y) - \mathcal{V}(x))^{+}$

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Comparison of algorithms

total selection intensities (depending on McKean models)

cloning algorithm $S_1^M(\eta) = |Q_k - 1| w(\eta)$ $mean-field$ $q_2^M(\underline{x}) = |Q_k - 1| \frac{1}{2M}$ $\frac{1}{2M}\sum_{i,j}\left|w(\eta^i)-w(\eta^j)\right|$ $S_3^M(\underline{x}) = |Q_k - 1|\frac{1}{2}$ $\frac{1}{2}\sum_i |w(\eta^i) - \mu(\underline{\eta})(w)|$

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Comparison of algorithms

 $k = -0.79$ k = 0.1

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time series
$$
\mu_t^M(\mathcal{V}_k)
$$
, $\Lambda_k^M(u,t) = \frac{1}{t-u} \int_u^t \mu_s^M(\mathcal{V}_k) ds$

cloning algorithm mean-field approximation

 299

Conclusion

Summary

- analyze and compare particle approximations via martingale characterizations
- adapt/generalize convergence results from sequential Monte Carlo

[del Moral, Miclo, Rousset,...]

• rigorous version of recent heuristic results on cloning algorithms

[Nemoto, Guevara Hidalgo, Lecomte (2017), Guevara Hidalgo (2018)]

Work in progress/open questions

- o asymptotic covariances and convergence to a stationary Gaussian process
- **e** extensions and potential improvement of cloning algorithms exploit freedom in McKean representations and particle approximations
- **•** numerical estimates for asymptotic variances

Thank you!

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